

Effect of dorsal or ventral hippocampus inactivation on goal-directed spatial navigation in rats and computational models Contreras M.¹, Llofriu M.², Weitzenfeld A.² and Fellous JM¹

. Introduction

- The hippocampus is essential for goal-directed spatial navigation.

- Previous studies have shown that dorsal hippocampal place cells possess small, stable, and spatially selective firing fields, while ventral cells have larger, less stable, and less spatially selective fields (Kjelstrup et al, 2008).

- Theoretical and modeling studies have suggested ways in which information along the dorso-ventral axis emerges and can be used for spatial navigation (Lyttle et. al. 2013, Erdem & Hasselmo, 2014, de Almeida et. al 2012, Monaco & Abbott 2011).

- The functional significance of these differences in memory-based goaldirected spatial navigation remains unclear.

- We hypothesize that the dorsal and ventral levels of the hippocampusentorhinal systems are differentially involved when the animal makes navigation decisions at multiple spatial scales.

- To test this idea we used a learning task in which animals had to memorize the locations of a set of rewarded feeders, and recall these locations in the presence of small or large obstacles.

2. Methods

Animals

- Male brown norway rats, 7-8 months old.
- Bilateral cannulae in Dorsal or Ventral Hippocampus.

Behavioral Apparatus

• Open field arena with 8 equally spaced feeders containing sugar water.



Objects: Lego blocks

• Experimental protocol.

Hippocampus inactivation

Memory Item= Set: 1,4,6 (in no particular order)

Small objects



Large objects





Infusion: Bupivacaine hydrochloride (bilateral, 2.5%, 1µl/side)

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Computational Modeling

• Multi-scale Q-Learning: Model Architecture.



Multi-scale Q-learning: Equation.

 $Q(s,a) = A(s) * [Q(s,a) + \alpha * (r + \gamma max_{a',s'} A(s') * Q(s',a') - Q(s,a))] + (1 - A(s)) * Q(s,a)$ Q(s,a): Q value of performing action a in state s, A(s): activation of cell s, α : learning rate, γ : reward discount factor

• Robot Model Aldebaran NAO v4.



3. Behavioral performance (Learning)

Performance of goal-directed navigation during learning



Rat's path is denoted by the blue line and the stops are denoted in green.

Recall performance was comparable for Set1 and Set2 without objects





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