**Estimation of Current and Future Physiological States in Insular Cortex**

**Highlights**
- InsCtx ongoing activity patterns reflect current bodily state, not behavioral state.
- Hypothalamic hunger/thirst neurons gate InsCtx responses to food/water cues.
- Hypothalamic hunger/thirst neurons do not gate InsCtx ongoing activity.
- Food/water cues drive transient “simulations” of future bodily states in InsCtx.

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**In Brief**
Livneh et al. find that slow changes in ongoing population activity patterns in insular cortex reflect physiological need states independent of behavior and hypothalamic hunger/thirst neurons. Food/water cues and consumption drive population activity to transiently “simulate” a future satiety state.
Estimation of Current and Future Physiological States in Insular Cortex

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SUMMARY

Interoception, the sense of internal bodily signals, is essential for physiological homeostasis, cognition, and emotions. While human insular cortex (InsCtx) is implicated in interoception, the cellular and circuit mechanisms remain unclear. We imaged mouse InsCtx neurons during two physiological deficiency states: hunger and thirst. InsCtx ongoing activity patterns reliably tracked the gradual return to homeostasis but not changes in behavior. Accordingly, while artificial induction of hunger or thirst in sated mice via activation of specific hypothalamic neurons (AgRP or SFOGLUT) restored cue-evoked food- or water-seeking, InsCtx ongoing activity continued to reflect physiological satiety. During natural hunger or thirst, food or water cues rapidly and transiently shifted InsCtx population activity to the future satiety-related pattern. During artificial hunger or thirst, food or water cues further shifted activity beyond the current satiety-related pattern. Together with circuit-mapping experiments, these findings suggest that InsCtx integrates visceral-sensory signals of current physiological state with hypothalamic-gated amygdala inputs that signal upcoming ingestion of food or water to compute a prediction of future physiological state.

INTRODUCTION

Interoception, the sense of the physiological condition of the body (Craig, 2003), involves sensing and integrating various signals related to heart rate, blood glucose levels, blood CO2 levels, temperature, inflammation, and more (Craig, 2003; Critchley and Harrison, 2013; Gogolla, 2017; Saper, 2002). Insular cortex (InsCtx) is the main cortical site that performs the integration of these signals from brainstem and thalamic sensory pathways (Saper, 2002), and is thus considered to be a key hub for interoception.

InsCtx is thought to mediate the interoceptive aspects of numerous behaviors, from feeding and drinking to social behaviors. Furthermore, InsCtx is implicated in pathological conditions including eating disorders, obesity, anxiety, major depression, and addiction (Barrett and Simmons, 2015; Critchley and Harrison, 2013; Frank et al., 2013; Garcia-Cordero et al., 2016; Gehrlich et al., 2019; Khalsa et al., 2018; Naqvi et al., 2014). However, the role of InsCtx in interoception remains unclear, as humans and rodents with lesioned or silenced InsCtx largely maintain habitual motivated behaviors such as eating and drinking (Livneh et al., 2017; Naqvi et al., 2014).

Prevailing models suggest that InsCtx receives sensory information regarding changes in bodily physiology (e.g., following food or water deficits) and integrates this with external sensory cues, associated action plans, and expected outcomes (Contreras et al., 2007; Kusumoto-Yoshida et al., 2015; Livneh et al., 2017; Naqvi et al., 2014). In particular, such models implicate InsCtx in computing “interoceptive predictions” (Barrett and Simmons, 2015; Owens et al., 2018; Paulus et al., 2019; Quadtl et al., 2018). Consistent with these active inference models, human and rodent InsCtx respond to salient predictive cues across different sensory modalities (Gardner and Fontanini, 2014; Kusumoto-Yoshida et al., 2015; Livneh et al., 2017; Vincis and Fontanini, 2016). In addition, human neuroimaging studies suggest that InsCtx represents physiological states, such as hunger and thirst (Egan et al., 2003; Meier et al., 2018; Tataranni et al., 1999).

Physiological need states, such as hunger and thirst, can serve as powerful models to study interoception. Each state involves specific physiological deficits that are sensed via interoceptive signals, ultimately giving rise to a specific motivational drive that helps correct the deficiency (Augustine et al., 2018b; Gizowski and Bourque, 2018; Lowell, 2019; Sterren and Eiselt, 2017; Zimmerman et al., 2017). These motivational drives can be recapitulated artificially via activation of distinct, genetically defined populations of hypothalamic neurons, such as hunger-promoting neurons expressing agouti-related peptide (AgRP neurons) and thirst-promoting glutamatergic subfornical organ (SFO) neurons (Aponte et al., 2011; Betley et al., 2015; Chen et al., 2016; Krashes et al., 2011; Oka et al., 2015). For simplicity and brevity, we will refer to these neurons as “hunger neurons” or “thirst neurons,” as they are thought to act both as sensors of physiological imbalances and as actuators of relevant behavioral and physiological counter-regulatory responses, including seeking and consummatory behaviors (Andermann and Lowell, 2017).
**A**
Conditioned stimulus | Action | Outcome
--- | --- | ---
Water cue | Lick | Water
Aversive cue | No lick | Nothing
Neutral cue | No lick | Nothing

Stimulus window (2 s) | Response window (2 s) | Inter-trial interval (6 s)
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**B**

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**C**
Two-photon imaging of InsCtx neurons

**D**

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**J**
Labeling of BLA cells with GCaMP6s

Two-photon imaging of BLA—InsCtx axons

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We recently developed a microprism-based method for cellular-resolution imaging of mid-posterior InsCtx in behaving mice (Livneh et al., 2017). We initially focused on hunger and found that InsCtx neurons showed selective responses to food-predicting cues that were abolished following satiation but restored following activation of AgRP neurons. Circuit mapping and pathway-specific manipulations defined a functionally relevant pathway linking AgRP neurons to InsCtx via paraventricular thalamus (PVT) and basolateral amygdala (BLA; Livneh et al., 2017). In the current study, we first asked whether these results generalized to thirst and water cues. We then considered whether InsCtx ongoing activity patterns represent distinct physiological states and how these representations might be integrated with those encoding need-relevant predictive cues. Our results suggest the following model: first, information regarding learned cues signaling the availability of food or water is relayed to InsCtx via a PVT-to-BLA pathway gated by hypothalamic hunger or thirst neurons. InsCtx activity then transiently shifts from a hypothalamic-independent estimate of current physiological state to a prediction of future physiological state.

RESULTS

We examined thirst-dependent InsCtx responses to water-predicting cues using behavioral procedures that we have previously used to examine hunger-dependent responses to food-predicting cues in InsCtx and other cortical areas (Burgess et al., 2016; Livneh et al., 2017). We trained water-restricted mice to perform an operant Go/No-Go visual discrimination task in which licking following presentation of three initially arbitrarily visual cues leads to rewarding (water), aversive (1 M NaCl), or neutral outcomes (Figure 1A). Well-trained thirsty mice quenched their thirst either by performing the task until voluntary cessation or by drinking water continuously in the absence of visual cues (intake of $\sim 0.5$–1 mL in $\sim 2$–5 min). We operationally defined a quenched state by voluntary, sustained cessation of water consumption (Figures 1B, S1A, and S1D).

We imaged GCaMP6f-expressing layer 2/3 neurons in InsCtx via a microprism (Livneh et al., 2017) in mice performing this behavioral task (1953 neurons in 12 fields-of-view [FOVs] from 9 mice across thirsty and quenched states; Figure 1C). As in previous studies, individual neurons could respond to the visual water cue, to onset of licking, or to water reward delivery (Figure 1D; de Araujo et al., 2006; Gardner and Fontanini, 2014; Katz et al., 2001; Levitan et al., 2019; Livneh et al., 2017; Samuelson et al., 2012; Stapleton et al., 2006). The majority of neurons ($\sim 80\%$) responded to either the water cue and/or water reward consumption, and $\sim 30\%$ responded to at least one learned visual cue (Figure 1E). Interestingly, neurons that were either activated or suppressed by the water cue were intermingled throughout mid-posterior InsCtx with no clear topographic organization (Figure S1B).

Average responses across sets of neurons that were activated or suppressed by visual cues were abolished after quenching of

Figure 1. Thirst-Dependent Bias to Water Cues in InsCtx Neurons and BLA-to-InsCtx Axons
(A) Schematic of visual discrimination task.
(B) Example task-related licking behavior across thirsty and quenched states. Left: lick rasters. Shading: 2 s visual cue. Right: mean $\pm$ SEM of 50–55 cue presentations.
(C) Two-photon calcium imaging of InsCtx through a microprism. Left: schematic coronal brain section and approach. Middle: example two-photon image of GCaMP6f-expressing neurons. Numbers correspond to traces in right panel. Scale bar: 100 $\mu$m. Right: normalized fractional change in fluorescence, $\Delta F/F$. Vertical lines: cue onsets (colors as in A and B).
(D) Example single neurons with time-locked responses to water cue, licking, or water. Top: heatmaps (rows: trials). Blue ticks: lick-bout onset; white ticks: water delivery. Bottom: average responses of the same neurons. Blue arrow: lick-bout onset. Scale bar: 20% $\Delta F/F$, 1 s.
(E) Fraction of neurons that responded to task events ($n = 1953$ neurons from 12 fields-of-view [FOVs] in 9 mice). Values: mean $\pm$ SEM across FOVs.
(F) Average population responses of neurons significantly activated (red) or suppressed (blue) by the 3 visual cues across states. Scale bar: 0.2 normalized $\Delta F/F$ (z-score across states). Values: mean $\pm$ SEM; $n = 581$, 204, and 221 neurons responding to the water, aversive, and neutral cues, respectively (9 mice).
(G) Heatmap of average neuronal responses to the 3 visual cues during thirsty and quenched states for all cue-responsive neurons. Vertical dashed lines: visual cue onset. Horizontal dashed lines: separation between sets of neurons, grouped by the cue that evoked the strongest response.
(H) Quantitative analyses of cue-responsive neurons. Left: fraction of all recorded neurons ($n = 1953$ neurons from 9 mice) responsive to each visual cue. Right: average response magnitude across thirsty and quenched states. Within state: $p < 2 \times 10^{-10}$, n.s.; not significant ($p > 0.13$), Kruskal-Wallis test. Pairwise comparisons (Thirsty): water versus aversive or neutral cue: $p < 1.3 \times 10^{-6}$; aversive versus neutral cue: $p > 0.22$. Pairwise comparisons (Thirsty versus Quenched): $p < 5.5 \times 10^{-4}$ for all 3 cues, Mann-Whitney test (neurons with significant responses to the water, aversive, and neutral cues: suppressed: $n = 324$, 175, and 180, respectively; activated: $n = 257$, 29, and 41; 12 FOVs, 9 mice).
(I) Comparison of cue responses between rapid and gradual quenching. Left: average population responses to the water cue across states following a rapid quenching protocol. Right: thirst modulation index for rapid and gradual quenching protocols (p = 0.2, Mann-Whitney test; $n = 100$ neurons from 3 mice for rapid quenching, $n = 387$ neurons from 6 mice for gradual quenching).
(K) Five example axons from (J). Left: regions-of-interest (colors denote different axons). Right: normalized $\Delta F/F$. Vertical lines: cue onsets.
(L) Example single axons with time-locked responses to different events: water cue, licking, or water. Top: heatmaps (rows: trials). Blue ticks: lick-bout onset; white ticks: water delivery. Bottom: average responses of the same axons. Blue arrow: lick-bout onset. Black arrow: water delivery. Scale bars: 10% $\Delta F/F$, 1 s.
(M) Fraction of axons that responded to task events ($n = 257$ axons imaged from 5 FOVs in 3 mice). Values: mean $\pm$ SEM across FOVs.
(N) Average population responses of BLA-to-InsCtx axons to the water cue across states. Scale bar: 0.2 normalized $\Delta F/F$ (z-score across states). Values: mean $\pm$ SEM; $n = 92$ cue-responsive axons.
(O) Quantitative analyses of cue-responsive axons. Top: fraction of all recorded axons ($n = 257$) responsive to each visual cue. Within state: *p < 0.01. n.s.: not significant ($p > 0.38$, Quenched), Kruskal-Wallis test. Pairwise comparisons (Thirsty): water versus aversive/neural cue: $p < 0.03$, aversive versus neural cue: $p < 0.04$. Pairwise comparisons (Thirsty versus Quenched): $p \leq 0.007$ for all 3 cues (except activated aversive cue responses with small sample size), Mann-Whitney test (axons responding to the water, aversive, and neutral cues: suppressed: $n = 66$, 12, and 13, activated: $n = 26$, 2, and 14, respectively; 5 FOVs from 3 mice).
Thirst (Figure 1F). Most cue-responsive neurons responded predominantly to the water cue in the thirsty state, with dramatically attenuated responses in the quenched state (Figures 1G and 1H). Importantly, we verified that these results were not due to different arousal levels across thirsty and quenched states. To do so, we used moment-to-moment changes in pupil diameter as a proxy for changes in arousal (McGinley et al., 2015), following our previously established procedure (Figure S1C; Livneh et al., 2017).

The sensation of thirst is affected not only by current fluid balance, but also by “subjective satiety” that accompanies anticipation of imminent restoration of homeostasis by fluid absorption (Augustine et al., 2018a; Gizowski and Bourque, 2018; Zimmerman et al., 2016). We thus compared datasets involving gradual quenching during tens of minutes of task engagement to datasets collected immediately following rapid quenching via 2–5 min of continuous consumption (osmotic balance is restored after ~10 min; Mandelblat-Cerf et al., 2017). We found similar attenuation of water cue responses following both gradual and rapid quenching protocols (Figure 1).

In summary, thirst-dependent InsCtx responses to water cues and drinking are similar to hunger-dependent InsCtx responses to food cues and feeding (Livneh et al., 2017). We and others have previously shown that BLA inputs are necessary for InsCtx predictive cue responses in both hungry and thirsty states (Livneh et al., 2017; Samuelsen et al., 2012). However, it remained unclear whether BLA inputs to InsCtx played an “instructive” role (i.e., relaying learned cue-related information) and/or a “permissive” role (e.g., providing necessary tonic activity but not relaying cue information; Wolff and Olveczy, 2018). We next addressed this by recording the activity of BLA inputs to InsCtx.

**Thirst-Dependent Response Bias to Water Cues in BLA-to-InsCtx Axons**

We expressed GCaMP6s in the BLA and used the same microprism preparation to image the activity of BLA axons in InsCtx (Figure 1J). We grouped together highly correlated signals from boutons belonging to the same axon (Figure 1K and Video S1; Burgess et al., 2016).

We imaged a total of 257 axons in 5 FOVs from 3 mice across thirsty and quenched states (Figure S1D). Single axons could respond to either the water cue, onset of licking, and/or water reward delivery (Figure 1L), consistent with previous studies (Baxter and Murray, 2002; Beyeler et al., 2016; Grewe et al., 2017; Kyriazi et al., 2018; Lutas et al., 2019; Morrison and Salzman, 2010; Zhang and Li, 2018) and with the broad collateralization of BLA-to-InsCtx axons (Livneh et al., 2017). The vast majority of imaged axons (~91%) responded to either the water cue and/or water reward, while ~50% responded to learned visual cues (Figure 1M).

Average visual responses across either activated or suppressed axons were abolished after quenching of thirst (Figure 1N). Similar to InsCtx neurons, cue-responsive BLA-to-InsCtx axons responded predominantly, and more strongly, to the water cue (Figures 1O and S1E). These results were not due to different arousal levels across thirsty and quenched states (Figure S1F; Livneh et al., 2017; Lutas et al., 2019). Similarly, BLA-to-InsCtx axons showed strong and selective food cue responses during a hungry state but not during a sated state (Figures S1G–S1K). Together, these data support an “instructive role” (but do not exclude an additional “permissive role”) for BLA inputs in relaying motivationally relevant learned cues to InsCtx. In contrast, gustatory information and visceral information regarding physiological states are likely relayed to InsCtx via other pathways (Samuelsen et al., 2013; Saper, 2002).

**Putative Representation of Thirst State in Ongoing InsCtx Activity**

Throughout our experiments, we observed high levels of ongoing activity in InsCtx even when mice were not performing the behavioral task (i.e., during quiet waking periods; Figure 2A and Video S2), consistent with the relatively high spiking rates in mouse InsCtx versus other cortical regions (Kusumoto-Yoshida et al., 2015; Levitan et al., 2019). Furthermore, some neurons had different levels of ongoing activity across thirsty and quenched states (Figure 2A). Human neuroimaging studies show that InsCtx tracks slow variations in physiological states, including hungry versus sated and thirsty versus quenched states (Egan et al., 2003; Meier et al., 2018; Tataranni et al., 1999). We therefore wondered whether mouse InsCtx ongoing activity during the task (in between cue presentations) might reflect aspects of physiological state. In this case, task-evoked neural responses would occur on top of physiological state-dependent patterns of ongoing activity (Arieli et al., 1996). Alternatively, ongoing activity could reflect other variables such as arousal or motor actions (Musall et al., 2019; Salkoff et al., 2019; Stringer et al., 2019).

To test this, we used a generalized linear model (GLM) to quantify the proportion of InsCtx activity that could be explained by behavioral task-related events and arousal state (Figure 2B; Driscoll et al., 2017; Ramesh et al., 2018). We modeled the activity of each neuron based on variables that describe task-related events (cue onset, licking, water reward, salt-water punishment), as well as arousal and body or brain motion (pupil diameter, locomotion, and estimated lateral motion of the imaging plane). Interestingly, the GLM could predict activity well only in a small subset of InsCtx neurons (fractional deviance explained: 0.13 ± 0.003; n = 1953 neurons from 9 mice; Figure 2C). In primary visual cortex (V1) neurons, which exhibit lower ongoing firing rates, robust visual cue-evoked responses, and strong sensitivity to arousal and locomotion (Andermann et al., 2013; Andermann et al., 2011; McGinley et al., 2015; Niell and Stryker, 2010), the fractional deviance explained by these factors was 2-fold higher during the same task (0.25 ± 0.01; n = 184 neurons from 3 mice; Figure 2C).

To directly examine InsCtx ongoing activity during gradual quenching of thirst, we focused on inter-trial interval (ITI) periods in between cue presentations. We minimized any residual effects of task-related activity by concatenating the last 3 s of ITI periods and only including ITIs that followed blank, aversive, and neutral cue trials for which mice did not respond (i.e., “correct rejections”; Figure 2D). Furthermore, we removed epochs that contained any licking. Notably, each selected ITI period occurred at least 13–25 s after the previous water reward (see Methods).
Figure 2. Thirst-Related Ongoing Activity Patterns in InsCtx

(A) Example activity of two InsCtx neurons during periods of quiet waking. Scale bars: 50% ΔF/F, 100 s.

(B) Activity of example neurons that are well fit (fractional deviance explained: 0.33) or poorly fit (0.1) by the GLM. Scale bar: 60 s. Dev. exp.: deviance explained.

(C) Distribution of GLM fits for InsCtx versus V1 neuron activity during the visual discrimination task.

(D) Schematic of the approach for analyzing ongoing activity restricted to a subset of ITIs not associated with any overt behaviors.

(E) Example ongoing activity (concatenated ITIs) of two InsCtx neurons across two days. Green dashed lines separate consecutive 30 min imaging sessions.

(F) Example ongoing activity of a population of InsCtx neurons. Left: two-photon images across two days. Scale bar: 100 μm. Right: ongoing activity of the same neurons across the two days. Blue lines: cumulative water consumption during the visual discrimination task. Green dashed lines: separation between consecutive 30 min sessions. Shaded pink rectangles highlight sets of neurons with similar changes in activity across states on both days. Blue/yellow rectangles: thirsty/quenched sessions in (G). Neurons were sorted by the difference in ongoing activity in Thirsty versus Quenched states on Day 1 (see color bars).

(G) Projection of population activity on the first three principal components (PCs) for the experiment in (F). Note that Day 2 data were projected onto Day 1 PCs.

(H) Classification of ongoing activity within day and across days. Classifier was trained on Thirsty and Quenched epochs (blue and yellow rectangles in F). *p ≤ 0.003, t test versus chance, n = 9 FOVs.

(I) Left: schematic side view of mouse brain. Right: anatomical location of all imaged neurons (dots) across mice. Dashed rectangles: borders of each FOV. A, anterior; P, posterior; D, dorsal; V, ventral.
We examined whether the pattern of InsCtx population activity during these concatenated ITI periods (referred to henceforth as “ongoing activity”) tracked hydration state during the visual discrimination task (n = 153 ± 25 neurons per FOV, 9 FOVs from 7 mice). Indeed, during a thirsty state, some neurons exhibited high ongoing activity that then decreased as mice became quenched, while other neurons exhibited the opposite trend (Figures 2E and 2F).

Using principal component analysis (PCA), we found that InsCtx activity patterns during thirsty states were separable from those during quenched states (Figures 2G, left and S2A). Moreover, these patterns and their separability were consistent across days, as demonstrated by projecting data from a given session onto principal components from the previous day’s session (Figure 2G, right). To quantify the separability of ongoing activity patterns, we took a classification-based approach. We used an Averaged One-Dependence Estimator (AODE) classifier, an extension of the Naïve Bayes classifier that also accounts for pairwise correlations between neurons (Sugden et al., 2018; Webb et al., 2005). Using this approach and within-day cross-validation, we could readily classify thirsty versus quenched states from ongoing activity. Strikingly, classification was high and above chance for all datasets, even when we trained the classifier on data from a given day and applied it to data acquired the following day (Figure 2H).

Classification of thirsty versus quenched states across days went to chance levels following random temporal shuffling of population activity patterns across the session (Figure S2B). Interestingly, while shuffling of neuron identities also reduced across-day classification in 9/9 cases, identity-shuffled population data still classified thirsty state above chance levels in some cases (Figure S2B). This suggests that a relatively large fraction of the population contained relevant information. Indeed, when we systematically omitted neurons, classification was reduced to chance levels only after omitting the most informative 40% of neurons (i.e., those whose activity differed most across states; Figure S2C). Furthermore, pairwise correlations were not essential for classification of thirsty or quenched states, as classification was similar using a Naïve Bayes classifier (Figure S2D). Importantly, the actual pattern of activity across the population was essential, as thirsty or quenched states could not be classified from a single time course of activity averaged across the population (Figure S2E). Notably, thirsty or quenched state classification was not a result of spatial organization, as neurons with increases or decreases in ongoing activity between thirsty and quenched states were spatially intermingled throughout mid-posterior InsCtx with no clear topographic organization (Figure 2I).

**InsCtx Ongoing Activity Reflects Physiological State Rather Than Arousal or Behavioral State**

Differences in InsCtx ongoing activity between thirsty and quenched states could potentially reflect differences in physiological state (e.g., systemic osmolarity) or differences in arousal and behavioral state. We next tested these interpretations.

The above analyses focused on across-day classification of thirsty versus quenched epochs. We therefore began by assessing how gradual changes in ongoing activity patterns relate to changes in behavior across the entire recording session using across-day classification (Day 2 data, Day 1 classifier). Surprisingly, ongoing activity could transition to a quenched state long before any overt change in task engagement (Figures 3A and S3A). Specifically, in 7/9 cases, ongoing activity transitioned to a quenched state while mice were still at peak performance, reflected by a similarly high rate of correct responses to the water cue pre- versus post-transition (100 ± 3% versus 100 ± 0%, p = 0.5, paired t test) and a similarly low rate of incorrect responses to other cues (p = 0% versus 4 ± 3%, p = 0.5). The transition in ongoing activity pattern to a quenched state occurred 3–25 min before any drop in task performance (Figure 3B) and was highly predictive of the eventual drop in task performance (Figure 3C) across a range of analysis parameters (Figure S3B). We also observed similar effects using an alternative method involving a scalar estimate of pattern similarity (Figure S3C).

To more directly test whether InsCtx ongoing activity represents physiological states or related internal states such as arousal or motivation, we asked whether ongoing activity dynamics (as reflected in dynamics of classifier state estimation) could be predicted by a combination of four parameters: (1) cumulative amount of water consumed (coarsely reflecting hydration), (2) pupil diameter (a proxy for arousal; McGinley et al., 2015), and (3) lick response latency and (4) lick rate on the most recent rewarded trial (reflecting motivational levels; Berdichevskaia et al., 2016; Figure 3D). A linear combination of all four parameters effectively captured ongoing activity dynamics across the session (R² = 0.8 ± 0.04; Figure 3E, see example in Figures S3D and S3E). We then systematically omitted different parameters and found that the only essential parameter for accurately predicting ongoing activity dynamics was the cumulative amount of water consumed. The omission of this parameter reduced the explained variance in 9/9 cases (R² = 0.56 ± 0.05). Omission of any of the other parameters did not substantially affect explained variance (Figure 3E).

We also considered the possibility that ongoing activity reflected time elapsed in the session (Wittmann, 2013). In a subset of mice (n = 6), we decoupled time elapsed in the session from amount of water consumed by also imaging during 10 min periods of forced task disengagement (no cues, no water delivery, and excluding time-points with licking; Figure S3F) partway through the training session. Ongoing activity was similar before and after these periods (Figure S3G), suggesting that the actual amount consumed—rather than time elapsed—drove the observed changes in ongoing activity. Interestingly, activity during these disengagement periods (which involved whisking, grooming, and other so-called “spontaneous” behaviors) was in some cases different from ongoing activity during prior and subsequent task performance. This is consistent with recent evidence of correlations between neural activity and these “spontaneous” behaviors in almost all examined brain regions (Stringer et al., 2019). Experiments involving artificial activation of hypothalamic thirst or hunger neurons or systemic injection of water provided additional confirmation that InsCtx ongoing activity does not reflect task engagement (see Figure 6).

We next examined whether distinct patterns of ongoing activity in InsCtx reflect fluid deficiency (thirst) and caloric deficiency.
Involving hunger and satiety (Livneh et al., 2017), suggest that more specific to a subset of areas including InsCtx. Additionally, distinct physiological states associated with hunger or thirst are represented in patterns of InsCtx ongoing activity. Trans-synaptic tracing experiments suggest a potential connectivity of InsCtx glutamatergic neurons drives thirst when using a variety of genetic or activity-dependent methods to target them (Abbott et al., 2016; Augustine et al., 2018; Leib et al., 2017; Marcian et et al., 2019).
We confirmed that SFO\textsuperscript{GLUT} neurons send sparse projections to PVT, while MnPO\textsuperscript{GLUT} neurons (labeled using vGLUT2-Cre or Nos1-Cre, which predominantly labels vGLUT2\textsuperscript{+} neurons; Allen et al., 2017; Augustine et al., 2018a) send dense projections to PVT (Figure 4B). We then used channelrhodopsin2 (ChR2)-assisted circuit mapping to test whether MnPO\textsuperscript{GLUT} neurons converge on the PVT-to-BLA-to-InsCtx pathway. We expressed ChR2 in MnPO\textsuperscript{GLUT} neurons and injected a retrograde tracer, CTB, in BLA. We then recorded light-evoked excitatory currents from CTB-labeled PVT-to-BLA neurons and found that 100% (41/41) received synaptic input from MnPO\textsuperscript{GLUT} neurons (Figure 4C). This suggests that many PVT-to-BLA neurons receive convergent input from both MnPO\textsuperscript{GLUT} and AgRP neurons, as ~70% of PVT-to-BLA neurons also receive input from AgRP neurons (Linen et al., 2017). Interestingly, a lower but substantial proportion of CTB\textsuperscript{+} PVT neurons (25/31, ~80%) also received synaptic input from MnPO\textsuperscript{GLUT} neurons. The convergence of GABAergic “hunger neurons” and glutamatergic “thirst neurons” onto the same individual PVT-to-BLA neurons suggests a potential antagonism or competition between these two drives at the single-cell level (see Discussion).

Finally, we tested the potential importance of this pathway in vivo by expressing ChR2 in MnPO\textsuperscript{GLUT} neurons (using vGLUT2-Cre) and activating their terminals in PVT (Figure 4D). This induced robust drinking (see also Allen et al., 2017; Leib et al., 2017) but not feeding (Figure 4D). The induction of drinking might be partially attributable to activation of collateral projections that we observed in the paraventricular hypothalamus and lateral hypothalamus (LH; Figure S4), consistent with recent reports of drinking-promoting LH neurons (Kurt et al., 2019). Together, these results suggest a potential convergence between hunger- and thirst-promoting hypothalamic neurons on a pathway to InsCtx (Figure 4A).

**Manipulations of Hypothalamic Hunger or Thirst Neurons Affect InsCtx Learned Cue Responses but Not Ongoing Activity**

We next tested whether activation of thirst neurons would restore InsCtx cue responses and ongoing activity patterns to those observed in thirsty mice. Lamina terminalis structures are reciprocally connected but hierarchically organized (Augustine et al., 2018a). Because available Cre driver mouse lines do
not necessarily exclusively label the thirst-related MnPO neurons, we used upstream SFOGLUT neurons as an entry point for artificial activation of the thirst circuitry (Augustine et al., 2018; Leib et al., 2017). We used chemogenetics (hM3Dq) to artificially activate SFOGLUT neurons as previously described (Figure 5A; Betley et al., 2015). We imaged InsCtx across natural thirsty and quenched states. We then injected the hM3Dq ligand clozapine-n-oxide (CNO) to activate SFOGLUT neurons. Remarkably, after SFOGLUT activation, all mice selectively licked to the water cue but withheld licking to other cues (Figures 5B–5D). Importantly, injection of CNO in the absence of hM3Dq expression did not induce drinking (Figure S5A).

SFOGLUT activation during a quenched state largely restored InsCtx cue responses to those observed during natural thirst (Figure 5E; n = 597 neurons from 4 mice). SFOGLUT activation, but not control saline injections, also restored the InsCtx water cue response bias (Figures 5F and S5B). InsCtx water cue responses following SFOGLUT activation in quenched mice were similar to those during natural thirst in ~70% of neurons. This was comparable to the level of similarity of water cue responses across two consecutive sessions during natural thirst, which likely reflects day-to-day dynamics of InsCtx cue responses (Figure 5G and 5H; Livneh et al., 2017). In addition, neurons’ cue response magnitudes were correlated between natural thirst and SFOGLUT activation (r = 0.3, p = 5x10⁻⁴). In summary,
SFOGLUT activation in a quenched state largely restores InsCtx water cue responses to a thirst-like state, similar to the restoration of food cue responses upon AgRP activation (Livneh et al., 2017). This led us to ask whether SFOGLUT activation would also restore thirst-related patterns of ongoing activity, which reflect a dehydration state (Figures 2–3).

We considered InsCtx ongoing activity during a two-day experiment. On Day 1, we imaged InsCtx during task engagement as mice gradually became quenched, as described above. We repeated this procedure on Day 2, but then injected CNO to activate SFOGLUT neurons following the transition to the quenched state (same mice as in Figure 5). As described in Figure 3, we trained a classifier on thirsty versus quenched epochs on Day 1 and tested it on all time points during Day 2. Surprisingly, we found that while SFOGLUT activation restored cue responses (Figure 5), it did not restore the pattern of InsCtx ongoing activity to a thirst-like pattern (Figures 6A and 6B).

These findings prompted us to ask whether the same would hold true for AgRP activation. We reanalyzed data from our previously published experiments using a two-day protocol across states of hunger, satiety, and satiety + AgRP activation (Livneh et al., 2017). We trained the classifier on hungry versus sated data from Day 1 and tested it on Day 2 data during satiety and AgRP activation (Figures 6C and S5C). We found that while AgRP activation restored cue responses (Livneh et al., 2017), it did not restore ongoing activity to a hunger-like pattern (Figure 6C). Therefore, our results suggest that InsCtx may maintain a faithful representation of a given physiological state, even upon activation of hypothalamic neurons that promote behavioral and InsCtx responses to need-relevant cues.

To further test this conclusion, we performed a loss-of-function experiment. Due to hierarchical organization of lamina terminalis thirst circuitry (Augustine et al., 2018a), we chose to inhibit its major output node: MnPO Nos1+ glutamatergic neurons. To do so, we chemogenetically inhibited MnPO Nos1+ glutamatergic neurons using hM4Di (Figure 6D), which has been shown previously to robustly suppress thirst (Augustine et al., 2018a). Inhibition of MnPOGLUT neurons in thirsty mice using the chemogenetic ligand Compound 21 (C21) strongly suppressed behavioral responses to water cues (Figure 6E, Day 2), while control saline injections did not (Figure 6E, Day 1). InsCtx responses to learned water cues were also strongly suppressed (Figure 6F). Importantly, C21 injection in the absence of hM4Di did not reduce task performance (Figure S5D).

We then examined InsCtx ongoing activity in a two-day experiment. On Day 1, we imaged InsCtx during a brief recording in the thirsty state, followed by a control low-volume saline injection. We then kept imaging across thirsty and quenched states as described above. On Day 2, we performed a brief recording in the thirsty state, followed by injection of C21 to inhibit MnPOGLUT neurons. Finally, we hydrated mice by systemic injection of isotonic saline (1 mL), which did not affect behavior but likely restored blood volume and, in part, blood osmolality. We trained the classifier on thirsty versus quenched states on Day 1 and tested it on Day 2. Strikingly, InsCtx ongoing activity patterns on Day 2 were largely similar between periods when dehydrated mice were engaging in the task versus when their task engagement was suppressed by MnPOGLUT inhibition (Figure 6G). Importantly, however, subsequent rehydration via isotonic saline injection caused ongoing activity patterns in InsCtx to become more similar to those observed during a quenched state (Figure 6G).

**InsCtx Responses to Learned Cues and Consumption May Reflect a Prediction of Future Satiety**

Theoretical models of human interoception suggest that InsCtx cue responses represent a prediction, or simulation, of a future interoceptive state (Barrett and Simmons, 2015; Owens et al., 2018; Quadt et al., 2018). Our data presented an opportunity to test this idea at cellular resolution across large populations of neurons in InsCtx of thirsty mice by comparing transient cue-evoked changes in neuronal population activity to the patterns of ongoing activity reflecting thirsty and quenched states. We hypothesized that presentation of a cue predicting water availability (and subsequent consumption of a drop of water) would rapidly modify the pattern of InsCtx activity to resemble the quenched pattern of ongoing activity within seconds, prior to absorption of water and changes in blood osmolality (Figure 7A).

During a thirsty state, neurons whose ongoing activity was higher in the quenched versus thirsty state increased their activity within seconds of water cue presentation, while the converse was true for neurons whose ongoing activity was lower in the quenched versus thirsty state (Figures 7B and 7C). Thus, the water-cue-evoked response reflected a shift in population activity pattern toward the quenched state. A similar shift occurred in 9/9 experiments from 7 mice (r = 0.32 ± 0.07). Accordingly, presentation of water cues during thirst caused a transient decrease in the classification of InsCtx activity patterns as matching the thirsty state (Figures S6A and S6B).

To more directly assess the relative similarity between the water-cue-evoked patterns and the ongoing activity patterns associated with thirsty and quenched states, we projected cue-evoked population activity patterns onto the axis traversing thirsty and quenched ongoing activity patterns (Figure 7A; Alien et al., 2019; Li et al., 2016) and scaled the resultant values between 1 (thirsty) and 0 (quenched). Water cues (but not other cues) and associated consumption during the thirsty state transiently shifted InsCtx activity patterns toward a quenched state (from values closer to 1 to values closer to 0) within seconds, despite the fact that water absorption occurs only minutes later and actual quenching occurs ~30–120 min later. This was true for individual mice (Figure 7D, left) and when averaged across all mice (Figure 7D, right). During gradual quenching across the session, ongoing activity patterns (prior to cue onset) gradually became more similar to those observed during the quenched state (Figure 7E; similar to results obtained with a classifier, Figure 3). Importantly, regardless of the current hydration state, water cues and associated consumption transiently shifted the pattern of activity, on average, to precisely the pattern associated with the future quenched state (Figure 7E).

These cue-evoked shifts were not simply due to the larger magnitude of neural responses to water cues versus other cues (Figure S6C), suggesting that they were caused by a change in the actual pattern of activity toward the quenched pattern. Furthermore, there were no systematic cue-evoked changes in population activity along a different axis linking activity patterns during high versus low arousal (i.e., large versus...
Figure 6. Manipulations of Hypothalamic Hunger and Thirst Neurons Do Not Affect InsCtx Ongoing Activity

(A) Top: example ongoing activity of an InsCtx population on the second day of the experiment. Bottom: classification of all time points. Classifier was trained on the previous day’s ongoing activity. Green dashed lines: separation between consecutive 30 min imaging sessions.

(B) Summary of classification of ongoing activity during “Thirsty” and “Quenched+SFOGLUT activation” across mice. *p ≤ 0.014; n.s.: not significant, p ≥ 0.38; t test versus chance (n = 4 mice).

(C) Summary of classification of ongoing activity during “Hungry” and “Sated+AgRP activation” across mice. “Hungry/Sated versus Hungry/Sated”: classifier trained on Hungry versus Sated on Day 1 and tested on Hungry versus Sated on Day 2. “Hungry/Sated versus Sated/AgRP”: classifier trained on Hungry versus Sated on Day 1 and tested on Sated versus “Sated+AgRP activation” on Day 2. *p ≤ 0.007; n.s.: not significant, p ≥ 0.87, t test versus chance (n = 4 mice).

(D) Experimental approach for chemogenetic inhibition of MnPOGLUT neurons (top left) while imaging InsCtx (top right). Bottom left: image of MnPO showing hM4Di-mCherry expression. Scale bar: 200 μm. Bottom right: two-photon image of InsCtx during MnPOGLUT inhibition. Scale bar: 100 μm.

(E) Summary of behavior across mice (n = 4). Correct water cue responses across conditions: p = 6.6×10⁻⁶ (one-way ANOVA), MnPOGLUT inhibition versus all other conditions: *p < 0.0005 (paired t test). All other comparisons were not significant. All tests include Holm-Bonferroni correction for multiple comparisons.

(F) Average population responses of all imaged neurons to the water cue during the different conditions. Scale bars: 0.5 normalized ΔF/F (z-score across states, within day).

(G) Ongoing activity across “Thirsty,” “Thirsty + MnPOGLUT inh.,” and “Rehydration” conditions. Left: classification of all time points. Classifier was trained on the previous day’s ongoing activity, Green dashed lines separate consecutive 15- or 30-min imaging sessions. Right: summary of classification of ongoing activity across conditions. “Thirsty” versus “Thirsty + MnPOGLUT inh.”: p = 0.08; “Thirsty” versus “Rehydration”: p = 0.015; “Thirsty + MnPOGLUT inh.” versus “Rehydration”: p = 0.04 (paired t test). All tests include Holm-Bonferroni correction for multiple comparisons (n = 4 mice). Values are mean ± SEM across mice.
small pupil axis, approximately orthogonal to the thirsty versus quenched axis; Figure 7F).

During a quenched state, water cues did not affect InsCtx activity patterns (values near 0 in Figure 7G, middle). We then activated SFOGLUT neurons during a quenched state. InsCtx ongoing activity patterns prior to cue presentation still reflected “quenched values” (≈0), consistent with the classifier results (Figures 6A and 6B). Remarkably, however, water cues now...
shifted activity patterns further along the thirsty-quenched axis beyond the quenched state to negative values (Figure 7G, right), suggesting a potential prediction of hypo-osmolality and/or hyper-volemia (see Discussion).

Similar findings were also apparent in InsCtx during hunger and presentation of food cues. Specifically, in hungry mice, food cues and subsequent consumption transiently shifted ongoing activity patterns to the future sated state (Figure 7H, right). Further, food cues presented in the sated state did not shift the pattern of InsCtx activity (values remained right). However, under AgRP activation during a sated state, InsCtx activity began at “sated values” (~0) and food cue presentation and food consumption then shifted the activity further along the hungry-sated axis beyond the sated state (Figure 7H, right). This may reflect a prediction of a physiological state associated with overconsumption.

**DISCUSSION**

We combined two-photon calcium imaging with circuit mapping and manipulations to investigate InsCtx representations of physiological need states and need-relevant predictive cues. InsCtx neurons exhibited a thirst-dependent water cue response bias, similar to their hunger-dependent food cue bias (Livneh et al., 2017). Two-photon imaging of BLA axons in InsCtx further implicated BLA as an important source of learned cue information for InsCtx (Livneh et al., 2017; Samuelsen et al., 2012). Different patterns of ongoing activity in InsCtx were associated with specific physiological states (thirsty versus quenched, hungry versus sated) in a manner that did not merely reflect behavioral engagement or arousal. Artificial activation of hypothalamic hunger or thirst neurons restored responses to need-relevant cues in InsCtx, potentially by converging on a common PVT-to-BLA-to-InsCtx pathway. However, this artificial activation did not restore InsCtx ongoing activity to patterns reflecting physiological states associated with food or water deficit. Furthermore, artificial inhibition of hypothalamic thirst neurons reduced behavioral and InsCtx responses to water cues, while ongoing activity was largely unaffected. These results suggest that physiological state information reaches InsCtx via pathways that are not gated by hypothalamus (Figure 8A). Importantly, during natural hunger or thirst, food or water cues transiently shifted InsCtx population activity toward patterns associated with future satiety states. During artificial hunger or thirst, these cues shifted the population activity beyond the satiety-related pattern. We propose that hypothalamic hunger or thirst neurons gate transmission of information regarding need-relevant cues to InsCtx, where these cue responses transform a representation of current physiological state to a transient prediction of a future physiological state.

**Circuit Mechanisms Underlying InsCtx Responses to Predictive Cues**

A large body of work in humans and animal models has established that InsCtx responds to learned cues predicting various salient outcomes (Becker et al., 2015; Fazeli and Büchel, 2018; Frank et al., 2013; Huerta et al., 2014; Kusumoto-Yoshida et al., 2015; Livneh et al., 2017; Naqvi et al., 2014). Recent work in rodent models has begun to reveal the circuit mechanisms that underlie hunger-dependent food cue responses in InsCtx (Kusumoto-Yoshida et al., 2015; Livneh et al., 2017). We now show that, as in humans (Becker et al., 2015), mouse InsCtx also exhibits thirst-dependent water cue responses, further supporting the generality of these findings (Figure 1; Livneh et al., 2017).

Pharmacological and chemogenetic silencing experiments by our lab and others have pointed to the BLA as critical for behavioral and InsCtx neuronal responses to motivationally salient cues during hunger or thirst (Kim et al., 2016; Livneh et al., 2017; Namburi et al., 2015; Samuelsen et al., 2012). We directly imaged the activity of BLA axons in InsCtx and observed both thirst- and hunger-dependent responses to water or food cues (Figures 1 and S1). Taken together, this evidence suggests that BLA plays an instructive role in the routing of salient cue information to InsCtx across different motivational states, including thirst and hunger.

We previously combined circuit mapping and manipulations to implicate a PVT-to-BLA pathway by which hunger, via hypothalamic AgRP “hunger neurons,” modulates InsCtx food cue responses (Livneh et al., 2017). Our current work suggests that thirst-promoting MnPO<sup>Glu</sup> neurons and AgRP neurons converge onto common PVT-to-BLA neurons (Figure 4). Intriguingly, PVT is also a site of convergence of other hypothalamic populations that promote distinct motivational drives, such as temperature regulation, aggression, and parental behavior (Hashikawa et al., 2017; Kohl et al., 2018; Tan et al., 2016). This convergence suggests that PVT may be a major hub that integrates information from multiple hypothalamic populations to modulate, and perhaps prioritize, cortical processing of need-relevant predictive cues (Figure 8B; Hashikawa et al., 2017).

**Physiological State Representations in InsCtx**

Neuroimaging studies in humans have suggested that InsCtx ongoing activity reflects hunger and thirst (Egan et al., 2003; Meier et al., 2018; Tataranni et al., 1999). Further, an elegant recent study showed that InsCtx is the only cortical site whose activity tracks bodily physiology and not “subjective water satiety,” while anterior cingulate cortex tracked subjective water satiety (Meier et al., 2018). These and other studies suggest that InsCtx integrates multiple types of sensory information to represent physiological hydration state (Augustine et al., 2018b; de Araujo et al., 2003; Gizowski and Bourque, 2018; Johnson and Thunhorst, 1997; McKinley et al., 2019; Zimmerman et al., 2017). However, the underlying neuronal population dynamics and circuitry remained unknown.

Using cellular-resolution population imaging, we showed that InsCtx ongoing activity patterns represent physiological need states (Figures 2 and 3). These representations were consistent across days, independent of behavioral engagement and arousal levels, and different for thirst and hunger. Most importantly, experiments involving artificial manipulation of hypothalamic hunger or thirst neurons allowed us to dissociate two aspects of InsCtx activity: ongoing activity patterns related to physiological state versus cue/consumption-related activity related to food- or water-seeking and consumption (Figures 5
Our findings suggest that InsCtx summates (Arieli et al., 1996) independent sources of input that convey information regarding either current physiological state (e.g., brainstem, visceral thalamus) or availability of food or water (BLA; Figure 8B). Analogous results have been observed for InsCtx gustatory function by dissociating cue- and taste-related InsCtx activity (Samuelsen et al., 2012, 2013). We speculate that BLA sends cue information to InsCtx, while InsCtx sends current and anticipated physiological state information back to BLA. This reciprocal loop might update the motivational salience and valence of predicted outcomes to inform decision-making (Klavir et al., 2013).

Recent studies in mice have found that fluctuations in behavioral state and arousal are major contributors to ongoing activity patterns throughout cortex, amygdala, and other subcortical structures (Allen et al., 2019; Gründemann et al., 2019; Musall et al., 2019; Salkoff et al., 2019; Stringer et al., 2019). Our InsCtx data likely contain information of this sort, particularly during periods of task disengagement (Figures S3F and S3G). Our analytical approach and conclusions rely heavily on exclusion of any data from periods involving overt behaviors (e.g., licking or consumption) and on the reliability of ongoing activity patterns across days. This allowed us to identify representations of physiological state that are largely distinct from those of behavioral state and arousal, or from any within-day imaging artifacts (e.g., axial drift in imaging plane). Several lines of evidence support this conclusion. Our findings were not dependent on task engagement, differences in arousal level (as reflected by pupil dilation), or time elapsed and were not observed in other cortical areas. Additionally, activation of hypothalamic hunger or thirst neurons, which induced the same behaviors that occur during natural hunger or thirst, did not modify representations of physiological state in InsCtx ongoing activity. Moreover, while inhibition of hypothalamic thirst neurons reduced motivated behavior and left ongoing InsCtx activity largely unaffected, partial systemic rehydration produced a robust shift in the pattern of ongoing activity to that associated with the natural quenched state. Critically, during both thirst neuron inhibition and systemic rehydration, there was...
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Recent models propose that interoception involves not only sensing of current bodily signals (Barrett and Simmons, 2015; Owens et al., 2018; Paulus et al., 2019; Quadt et al., 2018). These predictive coding models suggest that InsCtx should contain distinct representations of current physiological state and predictions of future physiological state, which can then be combined to compute interoceptive prediction errors. Consistent with this model, we found InsCtx representations of current physiological state. Furthermore, predictive cues and subsequent consumption of a single drop of water or food in thirsty or hungry mice shifted InsCtx activity patterns to precisely the pattern observed in ongoing activity during the future sated state, regardless of the current level of food or water deficit (Figure 7). These findings provide cellular-resolution evidence for the interoceptive prediction model of InsCtx function and open up new opportunities for future investigations of interoceptive prediction errors.

Our findings support a heuristic framework for the roles of ongoing and learned cue-evoked activity in InsCtx. Specifically, each of multiple need states may be represented in InsCtx via a specific activity pattern, distinct from the activity pattern during a replete state (eucaloric, euhydrated, euthermic, etc.), along a distinct axis in the space of InsCtx population activity (Figure 8C). This replete state activity may reflect a set point, static pressures. This is similar to recently proposed models (Juechems and Summerfield, 2019; Keramati and Gutkin, 2014) based on drive reduction theories of motivation (Hull, 1943). Furthermore, need-relevant predictive cues may transiently shift population activity along one or multiple axes (Figures 7 and 8C). Critically, readout of such population activity could allow estimates of both specific values along different axes and the overall predicted value of a given action. This framework could explain the contribution of InsCtx to decision-making.

This framework may also be relevant to understanding gustatory functions of InsCtx. For example, InsCtx represents taste palatability (Katz et al., 2001; Levitan et al., 2019), which predicts absorption of calories and necessary nutrients (sugar, salt, protein). Thus, taste-evoked InsCtx activity could represent a prediction of the physiological consequences of consumption. In addition, InsCtx is necessary for conditioned avoidance of a taste associated with subsequent malaise, possibly by transforming a palatable taste cue representation to one that predicts physiological aspects of malaise (Accolla and Carleton, 2008; Grossman et al., 2008; Lavi et al., 2018).

Compromised interoception is considered an important element of different psychiatric conditions, including eating disorders, addiction, anxiety, and mood disorders (Khalsa et al., 2018). Therefore, establishing animal models that can complement studies in humans will be crucial for developing a mechanistic understanding of InsCtx dysfunction in these diverse psychiatric conditions. Our current and previous studies (Livneh et al., 2017) provide a framework for achieving this goal. First, we developed an approach for sub-cellular resolution imaging of InsCtx in awake, behaving mice. Second, we demonstrated that mouse InsCtx recapitulates key findings in humans, and then took advantage of mouse genetic tools to provide mechanistic insights into the underlying neural circuit mechanisms. We now also make initial steps to test theories of interoceptive predictive coding in humans. We speculate that modified InsCtx cue responses and associated behavioral consequences in patients with eating disorders might reflect a difference in the InsCtx representation of the hungry and/or sated state (i.e., the set point). More generally, this framework should allow examination of potential dysregulation of central representations of current and predicted interoceptive states in a range of diseases in psychiatry and medicine.

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SUPPLEMENTAL INFORMATION
Supplemental Information can be found online at https://doi.org/10.1016/j.neuron.2019.12.027.

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AUTHOR CONTRIBUTIONS
Y.L., B.B.L., and M.L.A. designed the experiments and wrote the manuscript. Y.L. performed imaging, feeding and drinking studies, and data analyses. A.U.S. assisted with data analysis and provided conceptual input. A.U.S. and L.A.S. developed the AODE classifier. Y.L., V.I.F., and R.A.E. performed imaging, feeding and drinking studies, and data analyses. Y.L., B.B.L., and M.L.A. designed the experiments and wrote the manuscript.

DECLARATION OF INTERESTS
The authors declare no competing interests.

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KEY RESOURCES TABLE

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LEAD CONTACT AND MATERIALS AVAILABILITY

This study did not generate new unique reagents. Further information and requests for resources and reagents should be directed to and will be fulfilled by the Lead Contact, Mark Andermann ([manderma@bidmc.harvard.edu](mailto:manderma@bidmc.harvard.edu)).
EXPERIMENTAL MODEL AND SUBJECT DETAILS

All animal care and experimental procedures were approved by the Beth Israel Deaconess Medical Center Institutional Animal Care and Use Committee. Animals were housed with standard mouse chow (Teklad F6 Rodent Diet 8664; 4.05 kcal g⁻¹, 3.3 kcal g⁻¹ metabolizable energy, 12.5% kcal from fat; Harlan Teklad) and water provided ad libitum, unless specified otherwise. Mice used for in vivo two-photon imaging (age at surgery: 9-15 weeks) were instrumented with a headpost and a 2 mm microprism, centered over the mid InsCtx (see below and Livneh et al., 2017). All transgenic mice used in these studies were on the C57BL/6J background. For CRACM experiments, we used both male and female mice and did not observe any differences between them. We then used male mice for in vivo imaging and for food/water intake studies. Portions of the data in Figures 6, 7, and S3 involve new analyses of previous datasets (Burgess et al., 2016; Livneh et al., 2017).

METHOD DETAILS

Sample sizes were chosen to reliably measure experimental parameters, while remaining in compliance with ethical guidelines for minimizing animal use and keeping with standards in the relevant fields. Different animals in each experimental group served as replicates, and multiple repetitions of each cue also served as within-mouse replicates. Experiments did not involve experimenter-blinding, but randomization was used with respect to trial order and data collection. Animal subjects were not randomly allocated to experimental groups as all comparisons were performed within subject.

Behavioral training

After at least 1 week of post-surgical recovery, animals (10-16 weeks old) were water restricted to ~80% of their free-feeding body weight or food-restricted to ~85% of their free-feeding body weight. Animals were head-fixed on a custom 3D printed wheel for habituation prior to any behavioral training (10 min to 1 h over the course of 2-3 days). If the mice displayed any signs of stress, they were immediately removed and additional head-fixation sessions were added until there were no visible signs of stress. On the final head-fixation session, water-restricted and food-restricted animals were given water or Ensure (a high calorie liquid meal replacement) by hand via a syringe to acclimate them to licking water/Ensure. To train the animals to associate licking a lickspout with delivery of water/Ensure, we initially triggered delivery of water/Ensure (2-3 μL water, 5 μL Ensure - 0.0075 calories) to occur with every lick (with a minimum inter-trial interval of 2.5 s between Ensure deliveries). We tracked licking behavior via a capacitance-sensing lickspout (3D printed in a metal-containing filament connected to the MPR121 capacitance sensor). All behavioral training was performed using MonkeyLogic (Asaad and Eskandar, 2008).

Once water- or food-restricted and head-fixed mice reliably licked to obtain a water/Ensure reward, we introduced the water/food cue (‘Go’ trials involving an initially arbitrary visual stimulus, see below for more details). We initially trained animals by presenting the water/food cue followed by unconditional delivery of the water/Ensure reward (Pavlovian reward). Once animals were regularly licking in response to the Pavlovian water/food cue but prior to reward delivery, we transitioned them to delivery of an operant reward, conditional on the animal licking during the response window (i.e., during the 2 s post stimulus offset, see below for more details). After animals demonstrated stable licking behavior to the operant water/food cue (licking in response to > 80% of trials involving food cue presentation), we simultaneously introduced ‘No-Go’ trials involving presentation of an operant aversive cue or of a neutral cue. Licking during the response window of the aversive cue resulted in the delivery of 2-3 μL of 1 M NaCl for water-restricted mice and 1 mM quinine for food-restricted mice. Licking to the neutral cue had no outcome. Initially, we biased the total number of trials toward the reward cue (reward cue: quinine cue: neutral cue: 2:1:1), but over several days we slowly increased the fraction of aversive and neutral cue trials so that all visual cues were presented in equal proportions. Animals typically learned to perform the visual discrimination task in ~2 weeks. We have previously shown that the InsCtx bias to the reward-predicting cue is independent of this training protocol (Livneh et al., 2017).

We began all imaging and behavior sessions with 2-5 Pavlovian reward cue trials, which served as “behavioral reminders.” Pavlovian reward cue trials also occurred sporadically during imaging (5%-10% of trials). These trials were helpful in maintaining engagement, particularly during late stages of training. None of these Pavlovian reward cue presentations were included in the analysis of water/food cue responses.

The Go/NoGo task required water- or food-restricted mice to discriminate between square-wave drifting gratings differing in orientation. The LCD screen (Dell) used to deliver visual stimuli was positioned ~20 cm from the mouse’s eye. All visual stimuli were presented as movies designed in MATLAB (2 Hz and 0.04 cycles/degree, full-field square wave drifting gratings, 80% contrast; food cue: 0°, aversive cue: 270°, neutral cue: 135°; Burgess et al., 2016). All drifting gratings were presented for 2 s, after which the mouse had a 2-s window to respond with a lick. Licking during the visual cue was not punished, but also did not trigger delivery of the water/Ensure/salt-water/quinine. Only the first lick (if any) occurring during the response window triggered delivery of water/Ensure/salt-water/quinine. The lickspout was designed with two adjacent lick tubes (one for each outcome), such that the tongue contacted both tubes on each lick, which served as an effective deterrent for lick responses following aversive cues. Well-trained mice had a high rate of correct water/food cue licking responses (criterion: > 80% of trials, usually ~90%-95%), and a low rate of licking following aversive cue presentations (criterion: < 50%, usually ~20%-30%; Figures S1A–S1D).
Surgical procedures

Stereotaxic injections

Stereotaxic injections were performed as previously described (Livneh et al., 2017). Mice were anesthetized with isoflurane in 100% O₂ (induction, 3%; maintenance, 1%–2%), and placed into a stereotaxic apparatus (Kopf model 963 or Stoelting). After exposing the skull via a small incision, a small hole was drilled for injection. A pulled-glass pipette with 20–40 μm tip diameter was inserted into the brain, and virus was injected using an air pressure system (Picospritzer). A micromanipulator (Grass Technologies, model S48 stimulator) was used to deliver the injection at 25 nL/min and the pipette was withdrawn 5 min after injection. For postoperative care, mice were injected intraperitoneally with meloxicam (0.5 mg/kg). Mice were 8-14 weeks old at the time of injection, except for CRACM experiments, for which mice were 7-10 weeks old.

We used the following volumes of virus and injection coordinates: InsCtx (100–200 nl, Bregma: AP: 0.0, 0.4 mm, DV: −4.1, −4.3 mm, ML: −4.0 mm), SFO (50 nL per DV depth, Bregma: AP: −0.65 mm, DV: −2.3/−2.45/−2.6 mm, ML: 0 mm), MnPO (50 nl, Bregma: AP: +0.5 mm, DV: −5.2 mm, ML: 0 mm), ARC (200 nl, Bregma: AP: −1.45 mm, DV: −5.85 mm, ML: ± 0.25 mm), PVT (25–50 nl, Bregma: AP: −1.0, −1.3 mm, DV: −3.0, −3.0 mm, ML: 0.0, 0.0 mm), BLA (100 nl, Bregma: AP: −1.6 mm, DV: −4.5, −4.76 mm, ML: ± 3.3 mm).

Optic fiber implantation for optogenetic stimulation

First, mice were stereotaxically injected with AAV1-DIO-ChR2(H134R)-YFP into the MnPO, as described above. An optic fiber (200-μm diameter core; BFH37-400 Multimode; NA 0.52; Thor Labs) was then implanted over the PVT (AP: −1.3 mm, DV: −2.8 mm, ML: 0.0 mm from Bregma). The fiber was fixed to the skull using C&B Metabond (Parkell). Mice were allowed at least 3 weeks for recovery before behavioral testing started.

Microprism assembly and surgery

Glass microprism assemblies were fabricated using standard 2 mm prisms (#MCPH-2.0; Tower Optical) coated with aluminum along their hypotenuse. Prisms were attached to a coverglass (#1 thickness), both along the hypotenuse (to prevent scratching of the reflective surface) and at the side of the prism that faces InsCtx, using Norland Optical Adhesive 81 cured using ultraviolet light.

Approximately 1-2 weeks following AAV-GCaMP6f injection into InsCtx, mice (10-16 weeks old) were anesthetized using isoflurane in 100% O₂ (induction, 3%; maintenance, 1%–1.5%) and placed into a stereotaxic apparatus (Kopf) above a heating pad (CWE). Ophthalmic ointment (Vetropolycin) was applied to the eyes. Using aseptic technique, a custom-made headpost was secured using cyanoacrylate glue, dental acrylic and C&B Metabond (Parkell). A 2.2x2.2 mm² craniotomy was then performed over the left InsCtx and S2 (bottom edge of the craniotomy was just above the squamosal plate), centered around the AP location of the previously performed AAV-GCaMP6f injections. A 2x2 mm² microprism was then stereotaxically lowered into the craniotomy until contact with the InsCtx was made, and was then lowered further with concomitant movement medially (~100-200 μm) until contacting the top edge of the craniotomy, while verifying that the microprism’s bottom edge was inserted below the squamosal plate. Once the prism was in place, the window edges were affixed to the skull using Vetbond (3M), followed by C&B Metabond (Parkell) to form a permanent seal. A 1:3 dental cement mix of black powder paint (Black) and white dental acrylic (Dentsply) was then applied for light shielding. Meloxicam (0.5 mg per kg, s.c.) was administered and the mouse was allowed to recover. We imaged and included in analyses all animals with implanted microprisms and adequate microprism clarity for imaging.

Two-photon imaging across different natural and artificial states

Two-photon imaging was performed using a resonant–scanning two-photon microscope with tiltable scanhead (Neurolabware; 31 frames/second; 1154x512 pixels). All imaging was performed with a 20x 0.45 NA air objective (Olympus) with a 540 x 360 μm² field of view. All imaged fields of view (FOV) were at a depth of 90-200 μm below the pial surface, using a Mai Tai DeepSee laser (Newport Corp.) with laser power at 920-960 nm of 35-80 mW at the front aperture of the objective (power at the sample was likely substantially less due to partial transmission via the microprism). Imaging depth was adjusted in between runs (every 30 min) to account for slow drift in the z plane (< 7 μm).

Imaging across thirsty/quenched and hungry/sated states

To assay how changes in thirst/hunger state affect behavior and neural activity, we imaged mice during either gradual or rapid satiation. In the gradual satiation condition (only for water-restricted mice), we imaged mice during consecutive 30-min runs until the mice voluntarily stopped performing the task. We then performed one more imaging run, the ‘quenched’ run, in which mice did not respond to the water cue. We never observed re-engagement of the mice in the task during the quenched run, in contrast to re-feeding in food-restricted mice (Livneh et al., 2017).

In the rapid saturation condition, we imaged mice in two blocks of trials within a session, one block during water/food restriction and a subsequent block immediately following re-hydration/re-feeding. At the start of each imaging session, water/food-restricted mice (~80% or ~85% of free-feeding weight, respectively) performed the visual cue discrimination task. After ~180 trials (30-min imaging run), we provided the mouse with ad libitum access to water or Ensure until voluntary cessation of consumption. Water consumption lasted 2-5 min, while Ensure consumption lasted 45-75 min, using the same protocol for acclimating mice to the lick-spout (see above). During this period of time, mice consumed ~1 mL of water (in task involving water restriction) or ~3-5 mL of Ensure (in task involving food restriction) and then voluntarily stopped licking for rewards. We then imaged during an additional ~180 trials (30 min imaging run) while mice were quenched/sated (operationally defined as the absence of voluntary licking).
Importantly, we have previously shown that InsCtx cue response biases track motivational salience and are not observed in naive mice (Livneh et al., 2017).

**Imaging during chemogenetic activation of SFO\textsuperscript{GLUT} neurons**

We initially screened mice for successful targeting of AAV8-CaMKII-hM3Dq-mCherry to SFO by measuring CNO-induced drinking behavior (see details in ‘Water intake and food intake studies’ section below). If mice displayed significant drinking, they underwent further AAV-GCaMP6 injections and microprism implant surgeries, followed by behavioral training (see above). We then imaged mice across thirsty and quenched states, as described above. We verified post-mortem that mice that did not drink following CNO injection also did not express hM3Dq-mCherry in the SFO. We usually did not detect hM3Dq-mCherry anywhere in the brains of these mice, and therefore conclude that the injections were likely mis-targeted to the ventricle. Importantly, as CNO did not induce drinking in these mice, these experiments demonstrate that CNO itself is not sufficient to induce thirst in the absence of hM3Dq-mCherry expression (Figure S5A).

Following imaging during the quenched state, we injected 150 µl of 0.9% saline on Day 1, or CNO (5 mg/kg) on Day 2, waited 10-15 min and started another imaging run (~180 trials, 30 min). For every mouse used for these experiments, we used postmortem histology and immunohistochemistry (see below) to verify hM3Dq-mCherry expression in the SFO.

The effects of CNO injections were not due to the actual pain caused by the injection. First, we verified that saline injections did not restore behavioral responses or neuronal responses in the same mice on the previous day (Figure S5B). Second, all mice were habituated with several saline injections before performing the actual CNO injections. Third, it is highly unlikely that a painful stimulus, such as an intraperitoneal injection, would cause food cue-biased responses in InsCtx. It remains possible that this would cause a general long-lasting increase in arousal. However, as our pupil-tracking data demonstrate, this should result in a non-specific increase in responses to all 3 cues (Figure S1). Therefore, because CNO injections restored water-cue-biased responses (Figure 5) and InsCtx cue bias tracks motivational salience (Livneh et al., 2017), it is highly unlikely this can be explained by the actual needle injection, rather than by activation of SFO\textsuperscript{GLUT} neurons.

**Imaging during chemogenetic inhibition of MnPO\textsuperscript{GLUT} neurons**

We initially screened mice for successful targeting of AAV8-hSyn-DIO-hM4Di-mCherry to MnPO by measuring drinking behavior with 125 µl injections of 0.9% saline vs. Compound 21 (C21) (see details in ‘Water intake and food intake studies’ section below). If mice displayed significant, consistent inhibition of drinking, they underwent further AAV-GCaMP6 injections in InsCtx and microprism implant surgeries, followed by behavioral training (see above). Importantly, C21 did not affect behavior in the visual discrimination task in mice not expressing hM4Di (Figure S5D). The effects of C21 injections were not due to the actual pain caused by the injection, as control saline injections on Day 1 did not affect behavior (Figure 6E). For every mouse used for these experiments, we used postmortem histology and immunohistochemistry (see below) to verify hM4Di-mCherry expression in the MnPO.

**Consecutive days in states of thirst and then hunger (Figure S3I)**

We initially trained mice during water restriction on the water-seeking task. We then imaged mice while performing the task as usual on the first two days until they gradually reached a quenched state. After the second day’s imaging session ended, we returned mice to their home-cage overnight with free access to water, but no access to food. On the third day, the visual stimulus predicting water now predicted liquid food. Mice required some initial retraining at the beginning of Day 3. We used two different protocols. In protocol #1, the fluid reward was water and the food reward was Ensure. In protocol #2, the fluid reward was (calorie-free) 1 mM sucralose solution and the food reward was (calorie-containing) 600 mM sucrose, roughly matching both the sweetness of 1 mM sucralose and the caloric content of Ensure (Domingos et al., 2011).

**Pupil videography during two-photon imaging**

We acquired data using a GigE Vision camera (Dalsa) with a 60 mm lens (Nikon MicroNikkor) from a pre-selected region of interest around the eye ipsilateral to the LCD monitor used to present visual cues (contralateral to the InsCtx microprism). Acquisition of each frame (frame rate of 15.5 Hz) was triggered on every other frame of two-photon acquisition (acquired at 31 Hz) using Scanbox software (Neurolabware). The pupil was backlit with illumination originating from diffusion within the brain of the IR light used for two-photon excitation during imaging. See below for details of data analysis.

**Postmortem identification of imaging field location**

We performed this procedure as previously reported (Livneh et al., 2017). We terminally anesthetized mice with an overdose of chloral hydrate (Sigma Aldrich), and then left them in their homecage for several hours to reduce subsequent blood loss during decapitation. We then decapitated mice, and postfixed their heads in 10% neutral buffered formalin (Fisher Scientific) overnight. We carefully removed and washed the brains. We then performed whole-mount imaging of the entire brain using light and fluorescence microscopy for visualization of surface vasculature and GCaMP6f fluorescence. Microprism location was evident by a minor indentation of the tissue. We then aligned the postmortem surface vasculature to \textit{in vivo} epifluorescence images (imaged through the microprism) for coarse localization of the imaging field. For a more precise localization of the imaging field of view, we further aligned the vasculature to vascular landmarks from \textit{in vivo} two-photon imaging. Finally, we used this information to localize imaging fields of view, relative to the middle cerebral artery and rhinal vein. We verified that our imaging field location matched the locations in our previous study (Livneh et al., 2017).
Brain tissue preparation and immunohistochemistry
Mice were terminally anesthetized with chloral hydrate (Sigma Aldrich) and transcardially perfused with phosphate-buffered saline (PBS) followed by 10% neutral buffered formalin (Fisher Scientific). Brains were extracted, cryoprotected in 20% sucrose, and sectioned coronally on a freezing sliding microtome (Leica Biosystems) at 30–40 μm, and collected in 3–4 equal series. Brain sections were washed in 0.1 M phosphate-buffered saline pH 7.4, blocked in 3% normal donkey serum/0.25% Triton X-100 in PBS for 1 h at room temperature and then incubated overnight at room temperature in blocking solution containing primary anti-serum. The next morning, sections were extensively washed in PBS and then incubated in Alexa fluorophore-conjugated secondary antibody (Molecular Probes, 1:1000) for 2 h at room temperature. After several washes in PBS, sections were mounted onto gelatin-coated slides and fluorescent images were captured with an Olympus VS120 slide scanner microscope.

All antibodies used were previously verified. For all experiments that involved stereotaxic injections (e.g., anatomical tracing, ex vivo CRACM, optogenetic and chemogenetic behavioral and imaging studies), we verified infection in the desired brain region with minimal spillover outside it, and excluded animals with imprecise injections.

Rabies collateral mapping
Similar to previously described procedures (Betley et al., 2013; Livneh et al., 2017), three weeks after unilateral injection of AAV8-EF1α-DIO–TVA–mCherry into the MnPo/OVLT (in vGLUT2-ires-Cre mice), SADΔG–EGFP (EnvA) rabies was injected into the PVT (for coordinates, see above). Animals were allowed 5 days for retrograde transport of rabies virus and EGFP transgene expression in long-range axons before perfusion, tissue collection and imaging (Olympus VS120 slide scanner microscope). The GFP signal was amplified using immunohistochemistry to visualize weakly labeled axons.

Slice electrophysiology and channelrhodopsin-assisted circuit mapping (CRACM)
For brain slice preparation, mice 8–12 weeks old were anesthetized with isoflurane before decapitation and removal of the entire brain. Brains were immediately submerged in ice-cold, carbogen-saturated (95% O2, 5% CO2) choline-based cutting solution consisting of (in mM): 92 choline chloride, 10 HEPES, 2.5 KCl, 1.25 NaH2PO4, 30 NaHCO3, 25 glucose, 10 MgSO4, 0.5 CaCl2, 2 thiourea, 5 sodium ascorbate, 3 sodium pyruvate, oxygenated with 95% O2/5% CO2, measured osmolarity 310 – 320 mOsm/L, pH = 7.4. Then, the recorded cell at 10 mW/mm2. The light power at the specimen was measured using an optical power meter PM100D (Thorlabs). Thorlabs) was used. The blue light was focused onto the back aperture of the microscope objective, producing wide-field illumination and digitized at 20 kHz. To photostimulate channelrhodopsin2-positive fibers, a laser or LED light source (473 nm; Opto Engine; clamp mode, with membrane potential clamped at −70 mV). All recordings were performed using a Multiclamp 700B amplifier, and data were filtered at 2 kHz and digitized at 20 kHz. To photostimulate channelrhodopsin2-positive fibers, a laser or LED light source (473 nm; Opto Engine; Thorlabs) was used. The blue light was focused onto the back aperture of the microscope objective, producing wide-field illumination of the recorded cell at 10 mW/mm². The light power at the specimen was measured using an optical power meter PM100D (Thorlabs). The light output was controlled by a programmable Master-8 pulse stimulator (A.M.P.I.), and pClamp 10.2 software (Axon Instruments). The photostimulation-evoked EPSC detection protocol consisted of four blue light laser pulses administered 1 s apart during the first 4 s of an 8 s sweep, repeated for a total of 30 sweeps. We attempted to maximize our ability to detect light-evoked currents by biasing our recordings to cell bodies within the densest axon fields. In some experiments, TTX (1 μM) and 4-AP (100 μM) was added to the bath solution in order to confirm monosynaptic connectivity. All CRACM results presented are from 2-3 mice per group.

Water intake and food intake studies
We assessed drinking using Drinking Event Monitor cages (lickometer cages; Columbus Instruments). We put individual male mice into lickometer cages where licks on each bottle sipper tube were detected by electrical conductivity and recorded by a computer counter interface (Resch et al., 2017). Initially, for training and acclimation, we water-deprived mice overnight. The next day, we placed mice into lickometer cages with free access to a water bottle for 30 min. We considered training sessions successful if mice accumulated ≥200 licks during the test. If not, we repeated them the following day. For subsequent SFOGLUT chemogenetic activation and MnPOGLUT → PVT optogenetic activation experiments, we let mice have ad libitum access to food and water for 1-2 days and then tested evoked drinking.

For SFOGLUT chemogenetic activation, we measured drinking during two consecutive 30-min sessions. The first session was a control session 10 min following saline injection, and the second session was 10 min following CNO injection (5 mg/kg).
For MnPOGLUT chemogenetic inhibition, we water-restricted mice for 24 h, and measured drinking during a 30-min session, preceded by saline or C21 injection (5 mg/kg). Saline and C21 sessions were separated by two days and repeated 2-3 times per mouse, to verify the reliability of the effect.

For MnPOGLUT→PVT optogenetic activation, we firmly attached fiber optic cables (1.0 m length, 200 μm diameter; Doric Lenses) to fiber optic ferrules with zirconia sleeves (Doric Lenses). Light pulse trains (7-10 mW, 10 ms pulses of 20 Hz; 1 s on, 3 s off) were programmed using a waveform generator (National Instruments) that provided TTL input to a blue light LED (465 nm; Plexon). We measured drinking during two consecutive 30-min sessions. The first session was a control “light-off” session, and the second session was the “light-on” session. Optogenetic stimulation began 1 min prior to access to water. Blue light stimulation in mice with mis-targeted injections did not induce drinking.

We used the same mice for water and food intake studies. For food intake studies during MnPOGLUT→PVT optogenetic activation, we food-restricted mice overnight, and then measured the quantity of home-cage consumption during a two-hour period involving free access to chow. We measured feeding in “light-off” and “light-on” conditions on separate days, at least 4 days apart. For all water/food intake studies, we excluded from further analysis mice that demonstrated mis-targeted injections or fiber implants, or expression extending outside the area of interest, based on post hoc histological examination.

**QUANTIFICATION AND STATISTICAL ANALYSIS**

Statistical tests were performed using standard MATLAB (MathWorks) functions. Differences across mice (e.g., behavior) were tested using the t test due to relatively small sample sizes. Differences in neural activity across large neural populations were tested using non-parametric tests (Kruskal-Wallis and Mann-Whitney tests) due to the non-normal distribution of the data. We did not assume equal/unequal variance in parametric t tests, as all t tests were paired. All data analyses were performed using custom scripts in MATLAB (MathWorks) or ImageJ (NIH).

**Image registration and time course extraction**

First, each acquired image was spatially downsampled by 2X. To correct for motion along the imaged plane (x-y motion), each frame was registered to an average field-of-view using efficient subpixel registration methods (Bonin et al., 2011). Within each imaging session, each run (2-8 runs/session) was registered to the first run of the day. Image stacks were de-noised using principal components analyses (PCA) of every pixel across time, and by user identification and removal of noise principal components (low eigenvalues; based on Mukamel et al., 2009). Cell/axon masks and calcium activity time courses (F(t)) were extracted using custom implementation of common methods (Mukamel et al., 2009). To avoid use of cell/axon masks with overlapping pixels, we only included the top 75% of pixel weights for a given mask (Ziv et al., 2013), but users screened each prospective ROI and could edit the size of the mask, selectively removing the lowest probability pixels. We then excluded any remaining pixels identified in multiple cell/axon masks. We manually verified that all cell masks had typical cell body morphology and size. In order to not count an axon multiple times, each BLA→InsCtx axon regions-of-interest (ROIs) included signal from all boutons and the axon shaft (Burgess et al., 2016; Mukamel et al., 2009). To ensure we were not erroneously counting the same BLA→InsCtx axon multiple times, we calculated the pairwise correlation coefficient of all simultaneously recorded BLA→InsCtx axon time courses (all time-points, excluding 8 s epochs starting at water/food cue onset that include the cues, licking and water/Ensure reward, which could artificially drive strong correlations) and combined ROI masks with correlation coefficients higher than 0.6 (confirmed manually).

Fluorescence time courses were extracted by averaging the pixels within each ROI mask. Fluorescence time courses for neuropil within a 25 μm annulus surrounding each ROI (but excluding adjacent ROIs and a protected ring surrounding each ROI) were also extracted (Fneuropil(t): median value from the neuropil ring on each frame). Fluorescence time courses were calculated as Fneuropil_corrected(t) = FROI(t) − w * Fneuropil(t) + median(Fneuropil(t)). The neuropil weight (w) was calculated by maximizing the skewness of the difference between the raw fluorescence and the neuropil per day. The change in fluorescence was calculated by subtracting a running estimate of baseline fluorescence (F0(t)) from Fneuropil_corrected(t), then dividing by F0(t): ΔF/F(t) = (Fneuropil_corrected(t) - F0(t))/ F0(t). F0(t) was estimated as the 10th percentile of a 32 s sliding window of Fneuropil_corrected(t) (Burgess et al., 2016; Livneh et al., 2017). All example cue-evoked time courses were re-zeroed in the 1 s prior to visual stimulus onset for visualization purposes only.

**Alignment of cell masks across runs and across days**

We chose one set of cell masks for each day. All analyses for the alignment of cell masks across days were semi-automated with the aid of a custom MATLAB GUI. To align masks across two days, we first aligned the mean image from each day using one of three methods (depending on the degree of across-day image warping): a rigid body translation, an affine image translation (which allowed for across-day image rotation), or a Delaunay triangulation image transformation (for more complex image warping). The alignment transformation used to register the mean image from each day was then applied to each individual mask. For each pair of overlapping ROIs, we calculated the 2D correlation of the PCA/ICA masks. Any ROIs with correlation values below 0.05 were ignored, as were any correlations lower than 0.5 below the value of the maximum correlation. The remainder of PCA/ICA masks were shown to the user, along with an average image of the peak 200 frames of the activity of that ROI. We kept only those ROIs with high correlations in which
we could identify similar shapes of soma and processes in the maximum image on both days. Note that the image registration and warping techniques were applied to masks only for alignment suggestion purposes, and were never applied to cell masks for fluorescence time course estimation.

**Single-neuron response analyses**

We categorized cells as responsive to visual cues and/or licking and/or water/Ensure delivery. To determine if cells were responsive to visual cues, we independently tested the cue-evoked response of each cell to each type of cue for each day the cell was identified. For each cell, we compared activity in the 1 s prior to stimulus onset to activity in a 200-ms sliding window beginning at stimulus onset and continuing until 100 ms before licking onset. This helped minimize contamination of estimates of early, visual cue-evoked responses with activity linked to licking behavior. Given the variability of licking onset across trials, we only analyzed time-points that preceded lick onset by > 100 ms in at least 10 trials. The comparison of this post-stimulus activity with pre-stimulus baseline was performed using the Wilcoxon Signed-Rank test, followed by an FDR correction for multiple comparisons (p < 0.05). All data were analyzed using time-points up to 100 ms before licking onset. However, we also separately repeated this analysis using data up to 200 ms or 300 ms before licking onset, and observed similar results (Livneh et al., 2017).

As previously shown, InsCtx neurons can exhibit responses that are temporally locked to licking in the absence of any prior sensory cues, and can begin either just before or just after lick-bout onset. The same is true for gustatory responses to liquid tastants, such as those to water and Ensure (see e.g., Katz et al., 2001; Levitan et al., 2019; Samuelsen et al., 2012; Stapleton et al., 2006). Licking or water/Ensure responses can occur either just before (e.g., anticipatory) or just after licking or water/Ensure onset (i.e., somatosensory/gustatory). As such, to determine if cells were responsive to licking onset, we first aligned each trial to licking onset and tested whether activity changed significantly either just before (e.g., anticipatory) or just after licking onset. To assess responses that preceded licking, we performed the same procedure described above, but now comparing data during the one-second period prior to cue onset to the pre-licking period following cue onset. Additionally, to assess responses that occurred just after licking onset, we compared the 1 s period prior to licking onset to the period from licking onset until 100 ms before Ensure delivery. We followed a similar procedure for calculating responses to water/Ensure delivery. We first aligned each trial to the time of water/Ensure delivery. Then, to assess responses that preceded water/Ensure delivery, we performed the same procedure described above, but now comparing data in the 1 s prior to licking onset with data in the period prior to water/Ensure delivery. Additionally, to assess responses that occurred just after water/Ensure delivery, we compared the one-second period prior to water/Ensure delivery to the 4 s period following water/Ensure delivery. After these initial analyses, cells/axons were categorized as responsive to licking if they were responsive to licking in either the pre-licking or post-licking periods (or both), and categorized as responsive to water/Ensure if they responded in either the pre-water/Ensure or post-water/Ensure periods (or both).

We ultimately sought to coarsely categorize cells/axons as responsive to visual cues and/or licking and/or water/Ensure delivery. As described above, cells were initially independently classified as responsive to visual cues, licking and/or water/Ensure. However, cells/axons may have responses that start at one epoch (e.g., excited by licking) and continue well into the following epoch (e.g., excited by water/Ensure). In such cases, we would define its responsivity based on the earliest epoch for which the cell/axon was responsive, unless the response changed in sign in the following epoch (e.g., excited by licking and then suppressed by Ensure). Thus, if a cell/axon was significantly responsive in more than one epoch (visual cue, licking, water/Ensure), in order for it to be categorized as licking or water/Ensure responsive, its response to either epoch had to be of opposite sign (excited/suppressed) as compared to the previous epoch, for cells in which the previous epoch also evoked a significant response.

We also assessed response magnitude of the average cue-evoked response. For each neuron, we used the maximal absolute value of the average cue response during the time of presentation of the two-second cue as its response magnitude.

**Pupil diameter and its effects on cue-evoked responses (Figure S1C,F)**

We measured pupil diameter from videography of the eye. For the first frame of the movie, we manually drew a region around the eye and marked the center of the pupil. The center and area of the pupil was then fit using a custom implementation of the starburst pupil detection from openEyes toolkit and a ransac algorithm. The center position from each previous frame was used to initialize the subsequent frame.

For analyses of the relationship between InsCtx activity and pupil diameter, we used our previously established procedure (Livneh et al., 2017). We first up-sampled the pupil diameter time course (from 15.5 Hz to 31 Hz) using linear interpolation. Then we calculated the average pre-cue pupil diameter using the average of 1 s before the presentation of each cue during hungry/thirsty and sated/quenched states. We then matched pre-cue pupil diameter using the following procedure. For every cue presentation (trial) during a hungry/thirsty state, we searched for a matching trial during a sated/quenched state from the same session. We first searched for all ‘sated/quenched trials’ with pupil diameters that were within ± 10% of the ‘hungry/thirsty trial’. Of these, we then selected the ‘sated/quenched trial’ that had the value nearest to the ‘hungry/thirsty trial’. Each trial from both states could only be analyzed once. Using this procedure, we could match ~50% of trials from both states (because pupil diameter was typically slightly smaller, on average, during sated/quenched states, the ‘sated/quenched trials’ with higher pupil diameter values were usually matched to a given ‘hungry/thirsty trial’). We then analyzed InsCtx data either from all trials or only from trials matched for pre-cue pupil diameter (such that the distribution of pupil diameters across all trials used was similar between hungry/thirsty and sated/quenched states).
Comparisons across natural and artificial thirst states for individual neurons (Figures 1 and 5)

We first aligned data from the two days of the experiment and only used neurons that were active on both days and could be reliably identified on both days. To facilitate comparisons of responses across states within an imaging day, and across states between days, we normalized the responses of each neuron within day across states, using a single transformation that was applied to all cue responses from a given neuron within the same-day session. We accomplished this by z-scoring each neuron’s responses to the 3 visual cues across the two states within each day (i.e., z-scores from one distribution consisting of all cue presentations of all cue types during ‘Thirsty’, ‘Quenched’, and ‘Quenched+SFOGLUT activation’). Z-scoring was performed by \( (x_i - \bar{x}) / S \), where \( x_i \) is the \( \Delta F/F \) value at time-point \( i \), \( \bar{x} \) is the average \( \Delta F/F \) of all visual cue responses from that day (all time points from 1 s before cue onset up to 100 ms before the first lick per trial or 2 s post-cue onset in the case of trials in which no licking occurred during stimulus presentation; the average was across all trials, all visual cues, and all states), and \( S \) is the standard deviation of \( \Delta F/F \) from all visual cue presentations from that day (all time points from \(-1 \) s to \(-2 \) s relative to cue onset (up to 100 ms before first lick), across all trials, all visual cues, and all states). To capture changes from baseline, responses were re-zeroed such that pre-cue period mean was zero.

The ‘hunger/thirst modulation index’ was calculated for each neuron as \( (R_{\text{hungry/thirsty}} - R_{\text{sated/quenched}}) / (R_{\text{hungry/thirsty}} + R_{\text{sated/quenched}}) \), where \( R \) is a neuron’s average response during the entire visual cue (using time points up to 100 ms before the first lick in each trial, and for which such lick-free data existed for \( \geq 10 \) trials). We assessed similarity across days by using a three-step approach. First, we calculated a ‘state modulation index’ (SMI) that was identical to the hunger/thirst modulation index, but that was used to compare any two states, either within or across days (e.g., two consecutive thirsty sessions, or thirsty versus quenched). Second, to compare across-state similarity to inherent variability of responses over time in individual neurons, we also compared the similarity within state. We did this by assessing each neuron’s reliability (or ‘self-similarity’) by randomly splitting up trials within a session and state into two halves and calculating the SMI between the two halves, and then repeating this analysis 100 times, to obtain a distribution of self-similarity. Third, we compared the actual SMI across states/days to the neuron’s ‘self-similarity’ and classified it as similar if (i) both SMIs were between the 10th and 90th percentiles of the ‘self-similarity’ distribution and (ii) both SMIs had the same sign (excitation/suppression).

Generalized linear model of single neuron activity

To classify cell responses, we fit a Gaussian GLM to the activity of each cell (\( \Delta F/F \)), accounting for task and behavioral variables (Driscol et al., 2017; Friedman et al., 2010) using the glmnet package. We first downsampled the data by a factor of 2 and convolved the results with a Gaussian kernel of width 4 frames. We created a series of basis functions to describe task events and behavioral variables. These basis functions were a series of Gaussian curves separated by 4 frames, and with a full-width at half maximum of 4 frames. The basis functions spanned different time ranges surrounding each variable. We included the basis functions representing each cue type (food/water cue, neutral cue, and aversive cue), separated by trial type (hit, miss, correct reject, false alarm), and tiled across and beyond the entire cue duration (0–4 s). We also included basis functions representing times relative to (i) any stimulus offset (0 to 4 s surrounding offset), (ii) the presentation of reward outcome or aversive outcome ( 1 to 8 s), (iii) the onset of a lick bout ( 1 to 2 s from bout onset, with lick bouts separated by \( \geq 2 \) s), (iv) all other individual licks (one kernel at the time of each lick), (v) brain motion (the kernel convolved with the analog vector) and (vi) locomotion (the kernel convolved with the running speed) or pupil diameter (the kernel convolved with the analog vector). The GLM fit was on two thirds of the data for each cell with elastic net regularization (\( \alpha = 0.01 \)). We then used the GLM coefficients to measure the deviance explained on the remaining one third of the data (Figures 2B and C).

Estimation of InsCtx ongoing activity

We sought to minimize the effects of task-related activity on estimations of ongoing activity. To do so we used neuropil-subtracted fluorescence time courses (not yet normalized to baseline fluorescence), and identified times that would be minimally affected by task performance – the last 3 s of inter-trial intervals (ITIs, 6-8 s), preceded by correct rejection trials (no licking) of the aversive cue, neutral cue and blank trials. Notably, as a result, the previous rewarded trial was 13–25 s before the selected ITI period. Additionally, we removed any ITI epochs that had any licking. We then calculated the fractional change in activity (\( \Delta F/F \)) of the concatenated fluorescence time series of this subset of ITI periods using the sliding window method, described above. This approach allowed us to estimate ongoing activity levels that are minimally affected by task performance and by task-independent licking.

Classification of ongoing activity

We used an extension to the Naive Bayes classifier called an Averaged One-Dependence Estimator (AODE), which accounts for pairwise probabilities (Sugden et al., 2018; Webb et al., 2005) and does not make the false assumption that the activity of each neuron in a field of view is independent. The primary advantages of such a probabilistic classifier (i.e., one that uses Bayes’ rule) are that all assumptions are made explicit and the values determined by the classifier are simple probabilities. The equation for the AODE is below, where \( y \) is the class (e.g., thirsty/quenched), \( x_i \) and \( x_j \) are the activity levels of two cells, and \( \pi_y \) is the prior of class \( y \).

\[
P(y|x_1, ..., x_n) = \frac{\pi_y \prod_i P(x_i|y) \prod_j P(x_j|y, x_i)}{\sum_y \pi_y \prod_i P(x_i|y) \prod_j P(x_j|y, x_i)}
\]
We estimated the probability of a cell being active given a certain state by using the mean and standard deviation of its activity ($\Delta F/F$) in that state. We estimated the probability of a pair of cells being co-active given a certain state by using the Pearson correlation coefficient. For classification using Naive Bayes, we used the same estimations and formula, but without the terms involving pairwise probabilities of co-activity per state.

To facilitate comparisons across days, prior to classification, each neuron’s time course was z-scored per day. We then binned data into 1 s bins for classification. The classifier was trained on two classes (e.g., thirsty versus quenched), matching the number of observations per class. For within-day classification of these two classes, we used cross-validation (training on patterns from a randomly selected 80% of data and testing on the remaining 20% of data, repeated 100 times). For within-day classification of other imaging runs (e.g., between thirsty/quenched runs, SFOGLUT activation), we trained the classifier on the entirety of data from the two classes (e.g., thirsty versus quenched, matching the number of observations per class), and tested it on the other runs. For across-day classification, we trained the classifier on the entirety of data from the two classes (e.g., thirsty versus quenched, matching the number of observations per class) of a given day, and tested it on all runs from the other day’s data.

We shuffled time-stamps of population activity by randomly shifting the entire population vector (all simultaneously imaged neurons) in time and classifying thirsty versus quenched from the shuffled data. We repeated this procedure 100 times per FOV and presented results as the mean across the 100 shuffles per FOV (Figure S2B). Additionally, we shuffled neuron identity 100 times per FOV, classified thirsty versus quenched from the shuffled data, and presented the results as the mean across the 100 shuffles per FOV (Figure S2B).

Estimation of transitions between states (Figures 3A–3C and S3A–S3C)

We used the same approach to estimate the transition in behavior (task engagement) and in ongoing activity (classification) between thirsty and quenched states. We represented task engagement as a binary vector with values corresponding either to a correct response to the water cue (1), or an incorrect lack of response to the water cue (0). We represented ongoing activity as classifier probabilities of a thirsty state (range: 1-0). We calculated a running average of both of these vectors using the same window size, and set the crossing of 0.5 as the point of transition from a thirsty to a quenched state, but only if values remained below 0.5 for > 50 s of ITI time (corresponding to ~3 min of ‘real time’) to enhance robustness of the estimates and avoid noise from rare sporadic changes in estimated states. Importantly, varying the size of the sliding window did not affect our results (Figure S2E). We also used an alternative approach, based on actual pattern similarity. We used the same procedure described for the classifier above, but replaced the classifier with a scaled projection (values: 0-1) of activity from Day 2 onto the thirsty versus quenched axis from Day 1 (same procedure as in ‘Relationship between cue/consumption evoked activity and ongoing activity’, below, see also Figure 7A). This approach yielded similar results to the classifier-based approach (Figure S3C).

Predicting classifier dynamics from behavioral data (Figures 3D, 3E, S3D, and S3E)

We predicted ongoing activity dynamics (as reflected in dynamics of classifier state estimation) by a combination of four parameters: (1) cumulative amount of water consumed (coarsely reflecting residual water deficit), (2) pupil diameter (as a proxy for arousal; McGinley et al., 2015), (3) lick response latency on the last rewarded trial, and (4) lick rate on the last rewarded trial (3) and (4) reflect motivational levels; Berditchevskaia et al., 2016). We used “raw” (not binned or smoothed) classifier estimates for this analysis. We performed multiple linear regression using the MATLAB function ‘regress’, and used $R^2$ values to estimate the fit. We then systematically omitted parameters one by one, and tested how that affected $R^2$ values.

Relationship between cue/consumption evoked activity and ongoing activity

To correlate cue/consumption evoked activity and differences in ongoing activity, we used z-scored neuronal activity (as described above). First, we subtracted pre-cue values to estimate cue-evoked changes in activity from baseline. We then correlated this to the
difference in ongoing activity across states, $\Delta \text{State}$, calculated as $x_{\text{Thirsty}} - x_{\text{Quenched}}$, where $x$ is the mean ongoing activity in a given state (mean across all sub-selected, concatenated ITI periods described above; Figures 7B and 7C).

To assess cue/consumption-evoked changes in classification of thirsty versus quenched state from population activity, we trained the classifier on ongoing activity, as described above. We classified all population activity (including during ITIs and during cue presentation periods). We then examined classification in the peri-cue period without any additional normalization or re-zeroing of data (Figures S6A and S6B).

To project InsCtx population activity patterns onto the axis of thirsty versus quenched activity (Allen et al., 2019; Li et al., 2016), we defined this axis for each mouse by $x_{\text{Thirsty}} - x_{\text{Quenched}}$, where $x$ is the population vector of mean ongoing activity in a given state. We projected peri-cue activity onto this axis by calculating the dot product of this vector with the time-varying pattern of InsCtx population activity, $x(t)$. We then linearly scaled values along this axis per mouse, ascribing a value of 1 when $x(t) = x_{\text{Thirsty}}$, a value of 0 when $x(t) = x_{\text{Quenched}}$, and intermediate values for patterns that fell between $x_{\text{Thirsty}}$ and $x_{\text{Quenched}}$ (Figures 7D–7G). Note that values below 0 correspond to a position along this axis that is beyond the mean activity of the quenched state (i.e., patterns that are along the thirsty-quenched axis but that are even more dissimilar to $x_{\text{Thirsty}}$ than $x_{\text{Quenched}}$, and thus correspond to a putative state of overconsumption). We applied the exact same procedure to hungry versus sated data (Figure 7H). We similarly projected activity onto the High Pupil versus Low Pupil axis by using the mean population ongoing activity during periods when the pupil size was within the top or bottom 10% of the pupil size distribution, respectively (Figure 7F; using estimates of mean pupil size during the same set of ITI epochs of ongoing activity as described in Figure 2D).

To verify that the changes we observed following water cue presentation were not simply due to the larger magnitude of neural responses to water cues versus other cues, we scaled down the magnitude of the water-cue-evoked activity. We did this by scaling the dynamic pattern of responses to the water cue by the mean ratio between lengths of the mean evoked population vectors for the water cue and the neutral cue. This matches population vector lengths, without affecting the pattern of these cue response vectors (Figure S6C).

**DATA AND CODE AVAILABILITY**

The datasets and code are available upon request to the Lead Contact.